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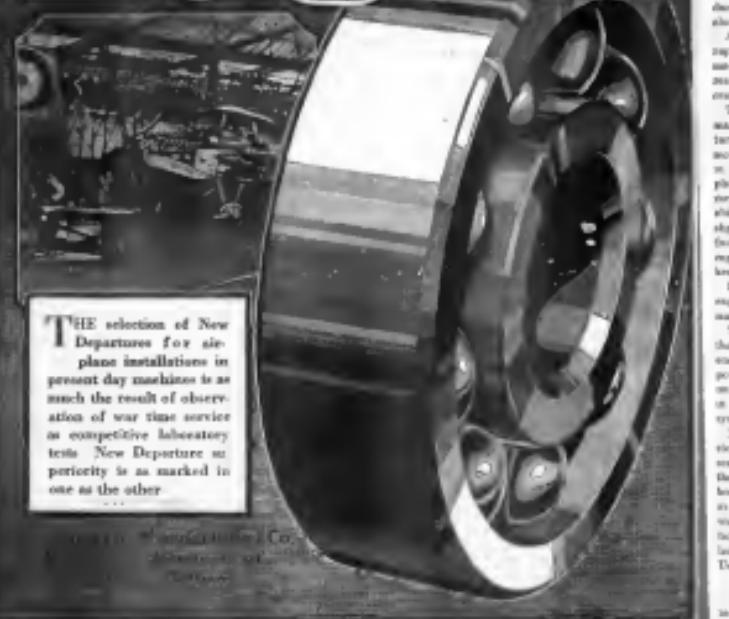
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No. 2

It is not true there was a system of licensing aircraft in use in America. Now that the war has been off and flying there is nothing to prevent a person from putting his own and a number of other people's lives and property in needless danger.

Driving an automobile is intended to be for easier than flying, yet no steps are taken by the state to make sure that a driver is competent before he is allowed to take a car into the air, while it is the universal practice that certain requirements must be fulfilled in order that a person may be permitted to drive a car. The skill and intelligence required in the two cases are not at all comparable, and the potential damage which can be done in the event of loss of control is also greater in the case of aircraft.

As at present constructed airplanes and airships are rapidly becoming as reliable vehicles as other automotive machines for transportation use. The conclusion is therefore reached that some sort of supervision should be maintained over aircraft by the state.

There are a number of ways in which control could be exercised. In the first place the machine should be structurally safe. In the early days of flying with the low-powered engines then available the quality of lightness was paramount in the structure. Very little structural engineering was applied to the designs, and many weak structures and the inevitable crashes resulted. Today we take pride in our ability to determine the strength of an airplane with but a slight degree of uncertainty, and instances of the structural failure of aircraft designed by a competent aeronautical engineer are rare. There should therefore be as difficulty in keeping this type of aircraft down to a reasonable quantity.

Stability and controllability are also well understood by the engineer and with proper precautions this source of danger may also be eliminated.

The remaining difficulty and the one which causes most of the crashes today is the failure of the power plant. The empty and the high duty demanded of an aeronautical power plant both detract from its reliability but they are unavoidable to a large degree. However, much can be done in the way of requiring approval of gasoline and cooling systems and motors.

In the event that the government refuses to take these or steps to the same effect—namely to protect passengers, passengers and the man on the ground alike—it is to be feared that research developments will result in a cheap and even hostile aircraft on the part of the general public toward aviation. The point is already being brought up in connection with aircraft insurance and we may hope for a correct solution of the problem by the insurance companies in the establishment of something analogous to the National Board of Underwriters.

Constant Torque

Many attempts have been made to maintain constant torque in an aeronautical internal combustion engine at altitudes. Most of the methods tried fall into one or the other of two

classes. The first, expediting, has been developed to a point where there is a certain measure of success in sight although the added mechanism is somewhat heavier and more unreliable than desirable.

The other is to increase the compression ratio at ground level beyond the value which will give best operating characteristics at that altitude. The compression will then fall at greater altitudes and operation will improve with the best ratio is reached at the height for which the motor is designed. A corresponding gain in power will then be shown over a motor with the same displacement but lower compression. A modification of this method which shows a still greater improvement in power at altitudes is to vary the compression ratio with the altitude by changing the length of stroke. Using this principle the optimum compression ratio can be obtained at all heights within limits imposed by the mechanical features of the device. A second result is the increase in displacement with stroke, which of course increases the charge.

With the latter method, the gain in power over the ordinary engine at 15,000 ft. is four times that obtainable with a constant compression motor of optimum compression. The weight of the stroke changing device is only 5 per cent of the engine weight, while the gain in power by its addition is 50 per cent, which is very much worth while.

Helpfulness of the Wright Lecture

The Wilbur Wright Lecture by Commander Blaauwker will do much toward simplifying and systematizing the design of the airplane in many important particulars. The appendices to the lecture are a source of information that designers may derive with great benefit. The analysis of the data there presented is very well carried out, and the conclusions drawn carry more weight than generalizations arrived at from a hasty standpoint alone. In fact a common sense attitude is maintained throughout the paper.

In the introduction of the conception of minimum height to surface model tests, a very useful method for interpreting and analyzing the vector motion effect on stability has been clearly explained. Much has been written on this subject but little has been stated in a form so lucid to the engineer as by the use of notations.

Control surface areas are successfully designed by empirical methods, and a mass of data on this important subject has been put in a form of great value to the designer. It is rather interesting to note the new advances in this particular branch of aeronautics. Helpfulness of the method rather than an advance in theory marks the progress.

Although there has been only a moderate amount of aircraft construction carried out in this country, it is pleasing to note from the previous instances of the day that there is a live interest being shown here in this branch of aeronautics. Those who may have apprehensions that we are not following the development of that type of craft may take some comfort from the attention given to the subject by Commander Blaauwker.

Determination of the Resistance of Airship Models

By R. H. Smith

West Point, U. S. Naval Yard, Washington, D. C.

Most of the early experimental work of aerodynamics on the head resistance of airship models has been done on one or the other of two standard types of aerodynamic balances, the Ruffel or the bell-crack type. The Ruffel balance is of French origin and takes its name from the celebrated French experimenter, while the bell-crack type is probably of American origin, being used in this country much earlier in 1908.

The bell-crack type is the more common of the two in American investigations, some of our balances being of this type. This is largely due to its directness and simplicity, which especially commended it as a means for smaller wind tunnels. In fact almost all wind tunnels under 20 sq ft section, and many of larger section—such as the 7-ft tunnel of the National Advisory Committee of Aeronautics at Langley, and the 20-ft tunnel of the Corps of Engineers at Garden City—are equipped with the bell-crack type.

The outstanding exception in America is the Ruffel balance in the three-moment balance which is mounted on our largest wind tunnel, the 68 sq ft section tunnel at the Navy Yard, Washington, D. C.

It would be well, therefore, in a discussion of wind tunnel tests on airship models to compare these two types as to their theory and subsequent design, and especially as to their merits for this class of work.

The Bell-Crack Type

The theory upon which the bell-crack types are designed to function is expressed in the simple equation

$$F = M/V$$

where F is the force to be determined, the resistance of an airship model for instance, M the moment which this force produces about the axis of a plane perpendicular to the wind, and V the velocity of the wind. The principal forces that an aerodynamic balance is required to measure are lift and drag, which act across and with the wind respectively, the bell-crack type has two principal moment axes, one parallel to and the other perpendicular to the airstream.

For simplicity in operation and design these balances are usually made with the two moment arms intersecting at the same point, the center of balance, and the moment arm in the plane. A drag or resistance force would therefore be determined from the moment it produced about the axis across the wind and from the distance from the knife edge plane to the line of action of the force. Since this moment arm must be known, the use of bell-crack types of balances is theoretically impossible, the only way to get around this difficulty is to use the bell-crack type for the longitudinal moment arm, and to make the transverse moment arm so long that the moment due to the wind force is small compared to the moment due to the surface flow in the wake of the spindle. This moment must be measured independent of the windage correction and in practice is found difficult to determine.

In order to reduce these correction difficulties, especially with the view of avoiding unnecessary disturbance of the surface flow, another method has been used for measuring and suspending the model. The windage correction is made of the weight in air at a position upstream from the balance beam by a reading on a long horizontal compression pan balance beam model steely. Although this correction is still necessary, requiring two independent correction tests, both lend themselves to accurate determination. The part of the total resistance due to the transverse moment arm is usually made so small as to be determined in the usual way with the deflected model held in position. A very satisfactory method for correcting for the exposed wire is discussed below in connection with the Ruffel balance.

It should be pointed out at the use of this method that the suspension wire must be of sufficient length to render negligible any component which they may have about the wind. The distance to light weight balance beam of the model is therefore determined where the fact is determined that the beam and deck stresses in tension of the spindle of an average bell-crack balance is at least twice the swing of the model at the end of the weight beam by which accurate balancing is effected. If the scale over which the wire swings is made with the scale over which the forces of the model swing may be taken as 0.02 in. or 0.03 in. It follows that the wire must be at least 12 in. or 18 in. long. The moment of the forces of the model is then divided by the weight of the model, and the ratio of the length of the suspension wire to the weight they carry, which is approximately the weight of the model, must be about 30 to 1. An average 30 in. will

Although Ruffel used a two-moment balance, assuming the

model first supposed thus inverted, the design of the Ruffel balance usually takes the general form of three moment arms arranged in the figure of a right triangle. Two axes, about which moments are taken for the determination of drag or moment, are set in a plane, perpendicular to the true axis, and two in a plane parallel to the true axis—the two a similar determination. The angle β between the two axes is the angle between the wire to the top arm of the triangle are no known quantities of the balance.

For accurate measurement of drag force this type of balance, when used normally, is at a decided disadvantage due to the serious loss of precision in taking the difference between quantities of about the same magnitude. If the ratio of the force from the two drag moment arms to the model is about 5 to 9, which are average values, the percentage error in the difference of the moments of the two arms in the form of a wire about 10 per cent, the percentage error in either moment arm, for the reason in measuring the resistance of airship models, the Ruffel balance is often used as a single moment balance and the arms measured from the moment arm to the point of application of the force. When used in this way, the Ruffel balance virtually becomes bell-crack and gives about the same precision.

The most serious difficulty, however, in the use of wind tunnel balances for airship resistance work lies not so much in their inherent precision, or lack of it, as in the problem of accurately determining the double influence of the exposed spindle by which the model is attached. The usual correction is based on a theory of "local" flow, which is a simple correction for the windage on the exposed spindle, this being always taken to keep the wind flow along the spindle the same as that during the test by detaching but not removing the model. For airship envelopes and other streamlined forms, however, which the resistance is due primarily to skin friction, the windage is presented with a steady force per unit as a longitudinal spindle attachment as well as a lateral force in the shield.

The equation upon which the use of this apparatus rests is $G = E d$ where E is the resistance in lb. of the displacement of the point of the model in in.

The magnitude of the resistance, E , is directly proportional to the displacement measured at the scale, and is independent of either the orientation or the weight before the scale.

To test on airship envelopes no deadweight is necessary. For such tests, therefore, the formula becomes simply

$$W = \frac{P}{R} \cdot d$$

where W is the weight of the model in lb. and d the distance from the point of suspension to the plane of the wind. Proper account should be taken of the weight of the wire, the beam carrying the model point and any other weights that may enter to increase the weight in the system.

Correlation displacements in testing airship envelope forms are obtained by a scale model about ten times the weight of the original model in lb.

The proper distance to suspend the model below the wind should be easily determined by measuring at some constant velocity, the scale displacements of an average airship model suspended at successive distances below the wind. By plotting the scale displacement versus the distance, it will be found that the curve levels from a straight line can be easily read. At this point the resistance of the model and wire no longer reduces proportionately to the length of wire exposed, indicating inflexion points of the curve at that position. The distance must should be 10 or 15 per cent more than the inflexion distance found.

Wire Corrections

While the bell-crack balances do not eliminate the spindle correction entirely, they do it much more diffusely by lengthening it in every instance with correction determinations. The method is as follows: a steel wire, of the same diameter as the suspension wire is run from the model parallel to and at the end of each suspension wire up into the shield where it terminates in a small clip attaching it to the suspension wire. The wires should be spaced about ten diameters to eliminate interference. The scale displacements are found at the vari-

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ous wind velocities with these free wires exposed. The two scale wires are then measured and with the two measuring wires exposed the test repeated. If the difference in the displacement is found to be constant, the displacements when two wires are exposed are the displacements for the model with no wire attached.

Due to wire resistance obtained in this way is obviously of no value in itself because for a well mounted model, the resistance of practically the full length of exposed wire is affected by the wind and by each model differently. Probably the most striking discrepancy in the data, incidentally, is in the wide variations in the exposure of the velocity with which the wire resistance seems to vary.

Pressure Gradient Correction

In addition to the wire or spindle corrections it has recently been found necessary to apply a correction for the buoyancy produced by a tail of air of finite length. This is a much more serious error in all models of more or less surface area. Only within the last year has this disturbing phenomenon attracted the attention of experimenters in this country.

This static pressure gradient correction is of considerable relative magnitude only on such streamline forms as airship envelopes. On aerofoils at these pressures the correction is negligible. On aerofoils the pressure gradient correction is likely to be as much as ten per cent of the resistance. On aerofoils envelopes the pressure gradient correction is probably at no more than 0.2 per cent of the drag and on surface models is much less. On aerofoils envelopes the pressure gradient correction is likely to be as much as ten per cent of the resistance.

The static pressure gradient correction is the integral of the pressure gradient correction over the surface of the model. The integral form is

$$p = \frac{1}{2} \int \frac{dP}{dx} \cdot dA$$

where P is the static pressure in lb. and x the envelope radius along any station along the model axis and dA is the surface area of the model at the point in in.

The magnitude of the resistance, E , is directly proportional to the static pressure gradient at the scale, and is independent of the orientation of either the orientation or the weight before the scale.

To test on airship envelopes no deadweight is necessary. For such tests, therefore, the formula becomes simply

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where W is the weight of the model in lb. and d the distance from the point of suspension to the plane of the wind. Proper account should be taken of the weight of the wire, the beam carrying the model point and any other weights that may enter to increase the weight in the system.

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Wind Tunnel

In practice it may often be found that the pressure gradient for the part of the tunnel remote from the model is such that the displacement of the model is not constant. In these situations whose gradients are constant, regardless of the power of V at which the static pressure varies at successive points along the tunnel, the reader of determining the static pressure gradient correction is radically simplified. Archimedean pressure gradients appear and it becomes a matter of multiplying the displacement at the point of interest by the pressure, a constant—the ratio of static pressure drop downstream—of static speed

The determination of these constants is quite simple. It is most easily done by drawing on logarithmic paper, with a scale marked for $\ln p$ per ft. on 21 static pressure and air streams marked for velocity, the two straight lines giving the variation of the static pressure with velocity for the two extreme points marking the up and down stream range desired. By taking the difference between the curves for any desired velocity, the pressure drop for the distance between the extremes (i.e. the rate of static pressure drop) is obtained in $\ln p$ per ft. per ft. These accuracy constants in $\ln p$ per ft. it would thus be obtained for all velocities and preserved as permanent calibration constants of the tunnel.

The method for correcting for constant pressure gradients has recently been developed and used at the wind tunnel of the Washington Navy Yard. This method, however, does not hold over the length of the tunnel occupied by the model.

Because static pressure calibrations are made when the air stream is undisturbed by the model, it may appear to the reader that the distortion of the gradient due to the presence of the model in the tunnel reduces the preceding discussion invalid. It is only to be expected to suggest that the distorted gradient is a part of the model itself, and that the air flowing in the tunnel section is large enough to affect the air stream in tunnel about the model as in an infinite stream—a natural change to be predetermined—the gradient is the natural flowing condition of the full sized craft. The only difference being that the model creates a gradient of some finite size, and the full sized craft creates a gradient of some finite size in a similar way—a gradient of approximately one sheet.

In aeronautics it might be well to note that the full static pressure drop across a sheet affects a slight change in the ρ and F terms of the resistance equation:

$$R = \rho A F \left(\frac{V^2}{2} \right)$$

causing ρ to decrease and F to increase. To eliminate uncertainty, assume an actual case in which the static pressure drop in a tunnel of constant grad rate, is at the rate of 0.01806 per sq. ft. per ft. of 30 m.p.h. This is equal to approximately a 0.0055 per cent drop in the static pressure across a 10 ft. of 30 m.p.h. The change in ρ and F is a mere fraction and small percentage reduction in ρ and increase in F for the same length of tunnel. This gives by inspection, since

$$\frac{dR}{dV} = \frac{d\rho}{dV} + \frac{dF}{dV}$$

a positive error in R due to the variation of ρ and F , of approximately 0.005 per cent for each foot the model is distant from the position of the Pitot tube or static pressure at which the velocities for the test are determined. This is true regardless of the position of the pitot along the stream in which the pressure gradient and atmospheric line intersect. The error of course is at most for the two end for consideration.

PROBLEMS

A complete pressure discussion of the results obtained by the balance would necessarily include a wide or long wide range of questions not strictly bearing upon the apparatus. Briefly speaking, however, the precision of the balance is tested by the equation

$$\frac{dR}{dV} = \frac{dR}{dW} \frac{dW}{dV} + \frac{dR}{dF} \frac{dF}{dV}$$

which follows from the equation

$$R = \left(\frac{W}{F} \right) d$$

It is always a simple matter to determine W to 0.1 per cent. The value of F , being a constant of the apparatus, can be determined to 0.1 per cent. The value of dF/dV is, however, to 0.05 per cent. The accuracy determination of d is more difficult, the precision depending largely on the accuracy of the wind velocity. By taking the average of a number of observations, however, such of which is taken when the wind velocity is as nearly correct as possible, the error in d at low velocities, that is 20 m.p.h., should not be more than 0.5 per cent and decreasing for higher velocities and larger displacements.

Consequently the largest error in R due to the uncertainty in determining W and d is said to result in about 0.7 per cent at 20 m.p.h. At 30 m.p.h. it should not be more than 0.4 per cent.

The other questions which enter into the overall precision of the results of the balance balances are questions over or less common to all other types of tunnel balances and comprising the next point, the presence of the various tunnel calibrations.

The direction of the air stream in the vertical plane must necessarily be known so that the model may be set at zero angle of attack. Although the angle of attack of the model varies with a small change of the wind velocities, this is very small compared to the rate of change of the lift, the percentage increase in the resistance due to the small increase in lift being many times the percentage error resulting from the lift change. The resultant weight of the model (An airplane of 4000 lb. in 30 m.p.h. at 10° angle of attack would have a 6.4 per cent increase in the resistance and an error in the measurement of the resistance of less than 0.02 per cent, due to the effect of the lift on the model weight).

Therefore, neglecting the lift on the model, the direction of the wind should be known to 0.25 deg to keep the precision of the mounting consistently within the precision of the test. Assuming that these errors do not present the velocities used in the test, the error in the lift is then determined by performing the model displacements. The precision of the agreement depends first upon the accuracy of the velocity calibration for that part of the tunnel section affecting the model, and then upon the accuracy of whatever calibration may be necessary in any particular case, to compensate for the difference between the mean effective velocity found and the velocity of the air entering the Pitot tube from which the velocities for the lift are determined.

If the wind velocities are obtained by a Pitot tube mounted on the windshaft for convenience, corrections for the effect of the shaft on the Pitot tube must be determined and accounted for in the calibration.

In order to check the last two corrections it will be found advisable to mount one Pitot tube at that point as the affected velocity is the most effective velocity, i.e., the velocity in the air portion of the Pitot tube. In the regular testing and for connecting each to a calibrated manometer determine directly what the readings of the regular speed Pitot should be to give correct velocities at the test position.

It is not difficult to do this calibration work with such accuracy that the total precision is well within the precision of a manometer reader when the velocities as fluctuating. The error in the reading of the velocity of air and the balance may therefore be added on the precision to which the manometer can be read. Since the accuracy of the manometer, which determines substantially the manometer fluctuation, is different for different manometers, the precision to which the velocity is known becomes a function, in each particular case, of the character of the manometer, and in a pressure discussion it is not unknown which such laboratory manometers do not measure.

The effect of the curve correction and pressure gradient correction on the precision of the balance balance data is as both cases negligible. While, in the case of the wire manometer, the displacement values for the model with no wires attached are theoretically, value for value, less than one third as precise as the displacement values for the model with two or four wires attached, to prevent the wires from being too near pressure in flowing and the errors in the test values and subtracting the latter difference. The legitimacy of doing this is based upon the long known fact that the resistance of streamlining forces comes as a single function of the velocity for the normal experimental velocity range. Consequently the resistance equation can be expressed as a simple linear equation, the resistance being zero when plotted on logarithmic paper, becomes a straight line.

It may be added in this connection that the linear logarithmic equation $R = K V^2$ has been shown to be true theoretically, only, if the factor (V/F) , which introduces the skin or surface friction in the more complete equation

$$R = \rho A F \left(\frac{V^2}{2} \right) + \frac{1}{2} C_d \rho A F V^2$$

also varies as a single function of the velocity, the function

being $V^{1.5}$. It is common knowledge on the contrary, that for very low velocities $n = 1$ and that it rapidly increases as the velocity increases. This has led to considerable suspicion on the applicability of the linear logarithmic equation. Tests on a number of airfoil forms, however, seem to indicate that n reaches a constant value, ranging from 1.82 to 1.92 according to the model, at a comparatively low velocity varying with the model, but apparently never exceeding 30 m.p.h. For some models a becomes constant at some velocity below 30 m.p.h. and continues to increase through 70 m.p.h., which is usually near the upper limit of the velocity range.

The error due to correcting for the pressure gradient is given less. The correction being less than 30 per cent of the resistance, these significant figures in the gradient corrections are all that can be used since the resistance values, to which the corrections are applied, are good not only to four significant places. The linear logarithmic equation gives the correct calibration values of the tunnel, however, should be determined to the fourth significant figure. Consequently, the third figure in the correction is more accurate than the fourth in the resistance, and a negligible error results from applying it.

It is, on the other hand, necessary that the constants of the tunnel be known in order that the errors in which the wind velocity can be satisfactorily minimized and determined.

The error due to correcting for the pressure gradient is given less. The correction being less than 30 per cent of the

The Pacific Hawk Commercial Airplane

The Pacific Hawk is a seaplane, enclosed, twin motorized biplane designed by O. W. Tilden, engineer for the Pacific Airplane & Supply Co., to meet the demand for a small low speed pleasure or commercial ship of the time rendered type

GENERAL DIMENSIONS

Span, upper plane	52 ft. 0 in.	lb.
Span, lower plane	52 ft. 0 in.	lb.
Chord, upper plane	6 ft. 6 in.	lb.
Chord, lower plane	6 ft. 6 in.	lb.
Gap between planes at fuselage	7 ft. 5 in.	lb.
Overall length	32 ft. 0 in.	lb.
Overall height	16 ft. 11 in.	lb.

Upper planes, (with ailerons)	320 sq. ft.	lb.
Lower planes, (with ailerons)	318 sq. ft.	lb.
Total area	638 sq. ft.	lb.
Airspeed, (best)	60 mph.	lb.
Stall speed	41 mph.	lb.
Elevation	41 mph.	lb.
Flight (gross)	3650 lb.	lb.
Endurance, (gross)	23 hr. 33 min.	lb.
Loadings, per square foot	6 lb.	lb.

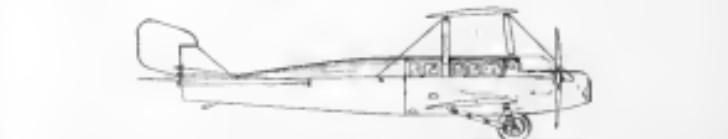
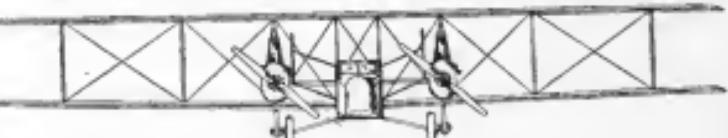
Length overall	30 ft.	lb.
Width	20 ft.	lb.
Depth (not including cabin)	10 ft.	lb.
Frontal area (not including cabin)	10 ft.	lb.

The main planes are of five sections. The ribs are designed from R. A. F. 6 data. Wings are of 1 section built up of three laminations of spruce. Ailerons are attached to both upper and lower planes and are 18 ft. long and 18 in. wide, constructed of wood.

FOOTPRINT

Length overall	30 ft.	lb.
Width	20 ft.	lb.
Depth (not including cabin)	10 ft.	lb.
Frontal area (not including cabin)	10 ft.	lb.

The front and rear floats are built of spruce and covered with plywood from the nose to the rear of the rudder and from the tail past to the side section. The balance is covered with balsa. The cabin is constructed of aluminum and Ultraply as used for windows. Three double window seats are set in. Dual Dep. control is operated from the front seat. One 40 gal. gasoline tank is mounted in the nose and one 30



FRONT AND SIDE ELEVATIONS OF THE PACIFIC HAWK

possible. Consequently the testing is carried on in a bath of oil where temperatures can be carefully regulated and watched. During the aging of the metal work cannot be done on it which would change the section as in that case the strength will not increase any more. After the completion of aging, the material can be re-rolled in order to obtain smooth surfaces. The strength is thereby increased at the expense of strength.

Fig. 2 shows the increase of strength during aging. The tensile strengths were determined by the Eisco test with 0.350 as a coefficient. The value was obtained from the experiments described below.

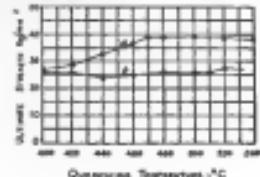


Fig. 3

Experiments have been made (see Fig. 3) by the Durener-Metallwerke to determine the most favorable quenching temperature. The curve "a" shows the variation in the strength of steel, which had been aged for four days with the variation of quenching temperature. Curve "b" shows the strength immediately after quenching. The strengths were determined in both cases by the Eisco test.

As the material may warp in tempering it is good practice to temper riveted parts. Such parts should be tempered before they are riveted.

EISCO TEST APPARATUS
Fig. 4

Strength Properties

Duralumin is delivered in various compositions which have different properties according to the purpose for which it is intended to be used. It is therefore important that the concern supplying the material should be informed regarding the nature of the working processes. In Table I below are summarized the strength figures of some duralumin compositions made by the Durener-Metallwerke.

The modulus of elasticity of the hard composition 601a

was found by the Technische Hochschule Aachen to be 190 kg/cm² per sq. cm. Making allowance for the possible effect of vibrations on the modulus of elasticity it appears better to use no more than 160 kg/cm² per sq. cm. in calculations.

In judging the suitability of a material for use in stressed parts one must pay particular attention to strength but the ductility is of great importance. This is best determined by bending strips backward and forward through 180 degrees over a definite number of times. It is to 10 times—the number of bends before fracture being taken as a measure. Other measurements as to the ductility can be obtained from the Eisco test (see Fig. 4). The plate to be tested is pressed through a ring, ϕ , by a load, P , until a tear occurs on the upper surface of the sheet. The depth of the impression is then a measure of the ductility.

In Table II there are compared strength values, number of bends (over 5 mm. radius and distance of 10 mm.) and depth of impression as determined on Duralumin plates and steel plates of equal thickness.

Although the strength values of the steel plates are less than those of the duralumin plates, nevertheless one can compare the figures as to "number of bends and depth of impression" with those of the duralumin plates.

From these figures, since it is possible to obtain steel plates with higher strength, which also possesses great ductility. The number of bends (see Fig. 5) for both metals decreases with increased thickness. For steel, however, they are considerably higher than duralumin. The difference in load for plates made of steel is also in thickness. For thicker plates the duralumin is less than that of the steel. For plates 2 mm. thick bending 5 times has a load of 100 kg. and bending 45 kg. load. For these results duralumin might be referred to as "soft steel" for thicknesses greater than 1 mm. This property makes it suitable for highly stressed parts which

must at the same time withstand vibrations. This is of great importance in connection with the test ing plate which are ordinarily used in aircraft for taking wire tensions. In these tests vibrations are produced by a weight which hangs in a vertical plane during a strong wind which would reduce the strength of the duralumin and might cause sudden fracture.

Hardly any information on the modulus of elasticity has yet been determined, although measurements of 160 kg/cm² per sq. cm. in this direction are already under way.

A comparison of the depth of impression of steel and duralumin is given in Fig. 6. It is shown that for steel the depth of impression increases with the thickness of the material while for duralumin it decreases. As a result of a peculiarity of the testing machine used the greatest stress occurred in a period which was from 5 mm. to 6 mm. from the center of the depression. In this locality the material begins to fail under the pressure. It is obvious that thick plates of duralumin material may be stretched more easily on the upper surface and consequently deeper impressions obtained than with thin plates, since for the plates of same material one has before them a greater ductility. It is also possible to use this method to explain the decrease of depth of impression with increasing thickness of plate in the case of material of less ductility.

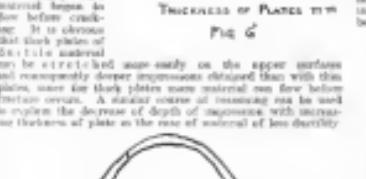


Fig. 6

Fig. 7
STEEL PLATE

degree, cracks very soon appear and extend into the interior. The process described can be followed as the action of a steel plate of about 40 kg./sq. cm. strength and a thickness of 1 mm. (Fig. 8). The flow before fracture of the steel plate is clearly recognizable while the duralumin plate shows hardly a sign of it.

Fig. 8
OUTSIDE FRACTURE OF DURALUMIN PLATE

Fig. 6 is a photograph of a test sample of strong duralumin plate after fracture in which the material suddenly split in all directions.

For drawing and pressing tempered duralumin is consequently suitable only in the thin gauge.

Influence of HEAT and COLD

Heat has an important influence on the strength of duralumin. According to the results obtained in tests by the Central Bureau for Scientific Investigation, when the temperature of the material is increased, the strength per unit area in tension of 100 deg. and about 20 per cent for an increase of 150 deg. (see Fig. 10). The loss in strength increases with the increase of temperature. The elongation increases on first heating to a fairly approximate curve, while between 150 and 200 deg. it decreases. At 200 deg. the strength

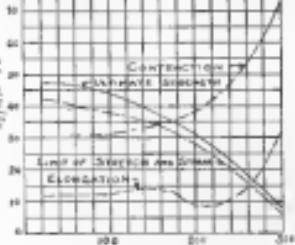


Fig. 10

decreases becomes the same as at room temperature. With further heating the elongation increases with increasing temperature. Consequently whenever duralumin is exposed to the sun the possible decrease of strength must always be considered.

As opposed to the foregoing, the influence of cooling on the strength properties is less favorable. The Central Bureau for Scientific Investigation has made tests on this also (see Table III).

TABLE II

Thickness of Plate	Strength, kg/cm² per sq. cm.	TESTS			EXPERIMENTAL
		Number of Bends	Depth of Impression, mm.	Strength in kg/cm²	
0.5	70	10.0	7.0	47	0.5 mm.
1	64	15.0	10.0	47	1.0 mm.
2	58	12.0	10.0	47	2.0 mm.
4	50	11.1	6.0	47	4.0 mm.
6	44	—	—	47	6.0 mm.

On the upper surface of the test pieces there were high tensile stresses at the point above mentioned, which account with the strength of the plate. As the material flows only to a small

TABLE III.

Influence of Heat on the Strength of Densitons					
Tested Temp per cent	The Air used is	Units of strain per cent	Tensile Strength kg. per sq. cm.	Expansion per cent	Strength lost by heat kg. per sq. cm.
+ 10	Air	44.1	49.5	20.0	3.0
0	Air	44.0	49.5	20.0	3.0
- 10	Mixture of air and table salt	44.0	49.7	20.1	2.7
- 20	Mixture of air and table salt	44.0	49.6	20.3	2.7
- 30	C. O. ₂ mix	31.0	49.4	20.7	2.7
- 40	Hydrogen	44.0	49.7	20.7	2.7
- 50	Air	21.0	49.3	20.8	2.8

TABLE IV.

Tension strain After heat		Effect of Weathering in New Strength kg. per sq. cm.	Effect of Weathering on the Strength of Densitons					
			1920 Strength kg. per sq. cm.	1920 Strength kg. per sq. cm.	1920 Strength kg. per sq. cm.	1920 Strength kg. per sq. cm.	1920 Strength kg. per sq. cm.	
Initial	0	44.1	20	43.0	20	42	19.5	19.5
Heat 10-20	10	44.0	20.7	43.6	20.8	43.8	20	20
Heat 20-30	20	44.0	20.7	43.6	20.8	43.8	20	20
Heat 30-40	30	44.0	20.7	43.6	20.8	43.8	20	20
Heat 40-50	40	44.0	20.7	43.6	20.8	43.8	20	20

The strength and elongation increase somewhat with the decrease in temperature. The work represented by the blow in the impact tests is not decreased, when the material is affected by cold, so that one can safely assume that the cold encountered in flight has no unfavorable influence on durability.

Experiments on the influence of weathering on the strength of densesitons, which have been carried on by the Deutsche Metallwerke for three years, have shown that an observable decrease in the strength proportion can be noticed (see Table IV).

The Deutsche Metallwerke have also carried on for about a year, experiments on the influence of the electrolytic effect from mixtures of densesitons with iron or steel. These were made by casting densesitons base to steel plates and then placing them in artificial salt water. These results only an inconclusive interpretation of the iron and a reduction in weight of the base of about 25 per cent so that no consideration exist against the use of densesitons and iron junctions in aircraft.

Summary

Densesitons has a strength of 35 to 48 kg per sq. cm. and an elongation of 10 to 25 per cent. The stretching stress limit has very high, about 25 to 30 kg per sq. cm. The modulus of elasticity is about 600,000 to 700,000 kg per sq. cm. It is very brittle, especially in thicknesses above 1 mm, and is especially sensitive to heating (up to 100° C. or more).

The book is well illustrated, although the types of construction shown are naturally limited. Details of construction are carefully considered, and sound methods of design given. Stress design is treated fully although the author is strongly in favor of the factor of safety. He neglects the last part of the volume in which trials of loads imposed on various parts of the machine under all the important conditions to which the machine is subject. The discussion includes the load factors which should be used for various types of machines.

Two chapters are devoted to strength tests of materials and structures, and the author gives a good account of the methods of testing and the meaning of the results.

The book is well written and is a valuable addition to the literature oferonautical engineering.

The book is well written and is a valuable addition to the literature oferonautical engineering.

Model Test for Strength and Deformation of Non-Rigid Airship Hulls

By Conradi, J. C. Hunsaker, C. C., U. S. N.

Suppose the model filled with water of buoyancy, is about 3000 kg. per cu. m., and the ship filled with hydrogen of a buoyancy equal to 11 kg. per cu. m.

Suppose the model made of some fabric as the ship.

Suppose the model scale n , which gives the same relative deformation as the ship, that is, the model, when deformed, is geometrically similar to the actual ship.

Suppose the model subject to an outer pressure such that the intensity of stress at corresponding points of model and ship are equal.

Geometric Relations. Call r_0 radius normal parallel and perpendicular to plane through axis of rotation meridian.

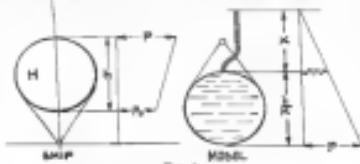


FIG. 1

the pressure on the belly is np , that is, a load of water given by —

$$x = \frac{np}{3000} \quad (1)$$

and the pressure p' at any point A corresponding to A' is given by —

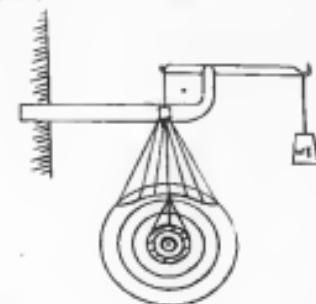


FIG. 2

At any point of ship's envelope there are two radii of curvature r_0 of the parallel and r_0' in the meridian through the point. If the pressure at this point is p , the tension in the fabric are —

$$p = \frac{p_0}{r_0} + \frac{p_0}{r_0'}$$

This equation is indeterminate because containing two unknowns p_0 and r_0 , but tension in a parallel is given by —

$$p_0 = \frac{p}{r_0} \cos A = \frac{p}{r_0'}$$

where A is slope of tangent to a meridian to axis. Hence p_0 and r_0 are determined as linear functions of the ratio of curvature, the pressure, and slope of the meridian —

$$p_0 = p_0 P \left[1 - \frac{p_0}{2 \pi r_0 \cos A} \right] \quad (2)$$

For corresponding points on model and ship, — and are constant. Hence for the same tension on both, the pressure must vary inversely as the ratio of curvatures or as n . The model has, therefore, the same pressure p at the ship, and the problem becomes that of arranging that the pressure ratios or pressure shall hold for all points, or that —

$$\frac{p'}{p} = \frac{n}{r_0} \quad (3)$$

Pressure Relations. — The buoyancy of hydrogen is $n = 11$ kg. per cu. m. and if the pressure at lowest point of balloon is p_0 kg. per cu. m. the pressure at a point A is given by $p = p_0 + 2.2A$.

In the water-filled model, letting weight down at its center, let us have a load of water as shown in Fig. 3, made that

$$p' = 1000 (x + R') \quad (4)$$

but by (4) —

$$p' = 1000 (x + R') \quad np + 1000 \frac{R}{n}$$

$$p = np + 1.1 \frac{R}{n} \quad np + 1.1 \frac{R}{n} = np + 1.1 R \quad (5)$$

and solving for n , we have —

$$p = np + 1.1 R \quad np + 1.1 R = np + 1.1 R \quad (6)$$

The problem is therefore solved by making a water-filled model to scale n and giving it a load of water above its water-line —

$$p_0 = 1.1 R \quad (7)$$

Then by (4) and (7) —

$$p' = np + 1.1 R \quad np + 1.1 R = np + 1.1 R \quad (8)$$

$$p = np + 1.1 R \quad np + 1.1 R = np + 1.1 R \quad (9)$$

$$p = np + 1.1 R \quad np + 1.1 R = np + 1.1 R \quad (10)$$

The load of water must then be $\frac{1}{3018}$ the load of hydrogen assumed for the ship. The pressure p_0 is roughly about 20 kg. per sq. m., which is an equivalent approx. length or load of gas $x = 18.2$ m. The load of water x will therefore be about 60.3 m.

To practice the necessary pressure p_0 to hold the balloon stiff will be found by substituting from the necessary water a found by experiment to hold the model stiff.

Reference: The ratio of volumes is n^2 and ratio of buoyancy —

$$\frac{B_{\text{ship}}}{B_{\text{model}}} = n^2 = \frac{3.1}{0.66} = n = 30.18$$

Hence model of 6600-lb. ship weighs 200 lb. approximately.



FIG. 2

In the ship the weight of hull is not carried by suspension, and may amount to as much as 25 per cent of total buoyancy. If the water model is hung upside down, the load on the

suspension is too great because it includes the weight of fabric. The weight of this fabric is $\frac{1}{n^2}$ of the weight on the ship since some stuff is used on both. For weights to vary as buoyancy, this should be only $\frac{1}{n}$ and hence 1/30 of current

weight. The total weight hanging on the suspension in therefore, greater relatively than on the ship and the conclusion is that the ship must be suspended in the water side.

This error may be corrected by putting on an air tank inside the model envelope to displace the required weight of water necessary to represent envelope weight. A tank is dispensed about one-quarter of the total volume is sufficient. Pressure and strain are not affected. The tank should be a long cylinder, tapered from end to end. An airtight tank which may be cut to form a straight tube with ends sealed and blown up with pump until the weight on the suspension is reduced 25 per cent.

The principal weight put on the envelope is the weight of gas and cushion, which may be estimated for the ship and a corresponding load be model — it is such applied when the ship does as shown in sketch.—*Aircraft Technical Note, Bureau of Construction and Repair, Navy Dept.*

Note on Measurement of Speed of Airplanes

By J. G. Coffin

Director of Research, Curtiss Aeroplane and Motor Corp.

The writer was very much astonished to learn that in air plane speed trials over a measured course it was considered necessary to wait for a time when little or no wind was blowing, or, if any, that it had to be along the course.

This, notwithstanding, of course, makes considerably the available time for the various trials, and, in fact, renders them impossible for days at a time.

While the writer does not believe that these restrictions are necessarily accepted he believes a short review of the subject



FIG. 1.

theory will not be out of place at this time and in particular a simple graphical method for the computation of the results which he has not seen published elsewhere is here given for the first time.

Consider a measured course AB of length S and let the observed time of flight from A to B be t, and the observed rate of flight from B to A be t' .

Assume that the wind speed W is constant in direction and magnitude during these measurements. The true relative speed of the airplane V is of course also assumed constant.

Referring to FIG. 1, let α be the angle the wind makes with the course. The longitudinal axis of the airplane makes some angle β with the course, and the resultant of the true relative speed of the airplane and the wind velocity must still be along the course. Let that resultant speed be U . On the return flight, let the angle made by the plane axis with the course be β' and the resultant speed along the course be U' .

It is quite evident that the component, normal to the course, of the vector V must be equal and opposite to the component normal to the course of the wind vector W , in both going and returning.

Hence

$$V \cos \beta = W \cos \alpha \quad (1)$$

$$V \cos \beta' = W \cos \alpha' \quad (2)$$

and hence

$$\frac{U \cos \beta}{U \cos \beta'} = \frac{V \cos \beta}{V \cos \beta'} = \frac{W \cos \alpha}{W \cos \alpha'} \quad (3)$$

Projecting the vectors W and V along the course we have

$$\frac{U_1}{U_2} = \frac{V \cos \beta}{V \cos \beta'} = \frac{W \cos \alpha}{W \cos \alpha'} \quad (4)$$

$$\text{Hence } \frac{V}{U} = \frac{d}{d \cos \beta} = \frac{1}{\cos \beta} \quad (4)$$

$$\text{and } \frac{W}{U} = \frac{d}{d \cos \beta'} = \frac{1}{\cos \beta'} \quad (5)$$

Also, from (1) and (4) and (5)

$$\frac{V \cos \beta}{U} = \frac{W \cos \alpha}{U} = \frac{1}{\cos \beta} \cos \alpha \quad (6)$$

$$\frac{V \cos \beta'}{U} = \frac{W \cos \alpha'}{U} = \frac{1}{\cos \beta'} \cos \alpha' \quad (7)$$

we get by squaring and adding

$$\beta^2 = \left(\frac{U_1}{U_2} \right)^2 + \left(\frac{U_2 - U_1}{U_2} \right)^2 \cos^2 \alpha \quad (8)$$

and similarly

$$\beta'^2 = \left(\frac{U_2}{U_1} \right)^2 + \left(\frac{U_1 - U_2}{U_1} \right)^2 \cos^2 \alpha' \quad (9)$$

$$U_1 \cos \alpha = \frac{U_2}{2} \quad (10)$$

$$U_2 \cos \alpha' = \frac{U_1}{2} \quad (11)$$

$$U = \left(\frac{U_1 + U_2}{2} \right) \cos \beta + \left(\frac{U_1 - U_2}{2} \right) \cos \alpha \quad (12)$$

Formulas (4) and (6) give the solution for V in terms of β and α respectively, while (5) and (7) serve to determine α in terms of β and β' respectively.

The following graphical method is a very simple one and solves equations (8) and (9)

Knowing S , t and t' compute U_1 and U_2 and lay off U_1 and U_2 as shown in FIG. 2 below, where $QW = QV$.



From M draw a line MP making angle β with U_2 , then MP is the true relative speed along the course.

$$\frac{U_1 + U_2}{2} = \frac{1}{\cos \beta} \quad (13)$$

If U_2 is known rather than β , draw QP making an angle α with U_1 , then draw MP as the true relative speed. From FIG. 2 we see that

$$\frac{U_1 - U_2}{2} = \frac{1}{\cos \alpha} \quad (14)$$

$$PQ = QV \tan \alpha = \frac{2}{\cos \alpha} \tan \alpha \quad (15)$$

$$MP = \frac{U_1 + U_2}{2} + \frac{2}{\cos \alpha} \tan \alpha \quad (16)$$

$$\text{Hence } U = \frac{U_1 + U_2}{2} + \left(\frac{U_1 - U_2}{2} \right) + \frac{2}{\cos \alpha} \tan \alpha \quad (17)$$

$$U^2 = MP^2 = \left(\frac{U_1 + U_2}{2} \right)^2 + \left(\frac{U_1 - U_2}{2} \right)^2 + \frac{4}{\cos^2 \alpha} \tan^2 \alpha \quad (18)$$

An error which is sometimes made is to divide twice the length S of the course by the sum of the two time intervals instead of using the correct equation (4).

That this error may occur can be seen by the following example, where for simplicity the wind is along the course, that is $\alpha = \beta = 0$:

$$\frac{U_1}{U_2} = \frac{U_1}{U_1 - W} = \frac{U_1}{U_1} \text{ whence the wind speed}$$

$$\text{computed by the erroneous rule is } \frac{W}{\frac{U_1}{U_2} - 1} = \frac{W}{\frac{U_1}{U_1} - 1} = W \text{ mph}$$

Let the wind speed and compute it such that

$$\frac{U_1}{U_2} = 100 \text{ mph}$$

$$\frac{U_1}{U_1 - W} = 100 \text{ mph}$$

The true speed is

$$\frac{U_1 + U_2}{2} = \frac{100 + 100}{2} = 100 \text{ mph}$$

$$\frac{100 + 100}{2} = 100 \text{ mph}$$

whereas the erroneous speed is

$$\frac{100}{\frac{100}{100} - 1} = \frac{100}{0} = \infty \text{ mph}$$

an error of 5 in ∞ mph.

It is better to determine β and use formula (4) than α first, because the amount and direction of the wind relatively

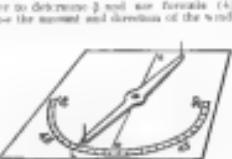


FIG. 3.

in the ground at the altitude of the airplane is the value required and these will probably differ from values observed at the ground. Second, it is not convenient to determine α from the airplane.

To determine β , on the other hand, is quite a simple matter and can be done as follows —

A horizontal board on which is pasted a slender scale divided into degrees, has a movable arm pivoted at the center and provided with two right angles at its ends. The board is attached to the machine so that the QW line is along the longitudinal axis of the machine.

The plane flies now to the test station, flies right along the course, and the angle QW which should be the angle going and returning is set for size. The average value of these angles is the β of formula (4).



FIG. 4

The course AB should be determined so that the two other points C and D are in line with AB. These points can be anything of prominence in the landscape, such as church steeples, prominent trees, water towers, etc., the idea being that starting somewhere between C and A the course AB is then kept "in line" in as far as the return starting somewhere between D and B the course BA is done, keeping AC in line.

There is an ingenious method derived from an English report which deserves mention here. Its advantage is that no reversion is needed. The airplane flies on as far as at a constant altitude directly over the observer who sights with a transit, reading off the angles α , after a given time interval has elapsed. The method is shortly described below.

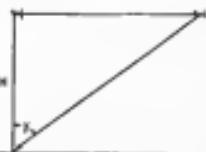


FIG. 5

In still air, or an airplane starting from a given point Q flies in three or more directions, the speeds will all be equal and the ends of the velocity vectors etc., will lie on a circle. QV, QW, QX, etc., are observed airplane speeds. The radius of circle is the true airspeed air speed, QV' is true wind velocity.



FIG. 6

Hence the method. Determine the ground speeds in three or more directions. Plot these vectors and by means of a transparent set of concentric circles find the one with center Q' that passes through the points Q, QV, QW, etc. The radius of this circle is the true airspeed air speed, QV' is true wind velocity.

Wind Tunnel and Airship Model Testing

By R. N. Wing

Accommodation Engineer, Goodyear Tire and Rubber Co.

The information obtained from wind tunnel tests on models of complete airplanes, airships and their various parts has been of utmost value in the rapid development of aircraft during the last decade.

The wind tunnel and tunnel testing is to investigate the action of the air around bodies moving through it and to measure the resulting air forces at various speeds upon these bodies under various conditions. The fundamental principle upon which wind tunnel testing is based is that of "relative motion," which is, basically, that the reaction between a body and the air is the same as the reaction between the air and the body. Hence, still air or a certain speed or whether the body is held immovable, and a stream of air of same relative velocity and direction impinges upon the body.

Methods of Aerodynamics Testing

Before going into a detailed description of the wind tunnel, let us first briefly the various methods of obtaining aerodynamic data. There are three methods of testing the airship and the wind tunnel. We will not here consider the testing of the full size machines or airship flight, but such tests should be taken advantage of for checking the other methods whenever possible.

(1) **Flight Method.** This method, used at the Aeroplane Inspection Bureau, U. S. Army, covers the use of full size machines, and even full size airships. The apparatus consists of an airship air which is operated along a straight track one mile long and above which are supported the surface to be tested and the measurement instruments.

The main disadvantage of this method is the inability to obtain static air, and it is generally necessary to repeat a test at least once to determine the effect of the wind on the change in aerodynamic drag or velocity. Because of the high speeds of test, the resulting sheet of air is of little use for experimental observations unless the position of the results.

(2) **Wind Tunnel.** This method is used by the Victoria Co. of London on test propellers. This apparatus consists of a large wind tunnel 12 ft. radius which revolves about a vertical axis. The air stream is taken at the outer end of the revolving arm. The measuring instruments are taken out of the centrifugal frame. A large taildragger leaves this apparatus. The large wind tunnel of the U. S. Navy Department is an E. D. square tunnel of this type and is operated by means of a 500 hp. electric motor driving a suction blower. A wind velocity of 15 mph. may be obtained, but tests are generally made at a speed of about 60 mph. Models of both airplanes and airships are tested in this tunnel.

(3) **Wind Tunnel.** This apparatus consists of a channel through which air is drawn at a known velocity by means of an exhaust fan or propeller. The wooden or metallic model to be tested is mounted in the channel upon an aerodynamic balance by means of which the various air forces are accurately measured, namely, drag or drag, which is the horizontal component of the force of air, lift, which is the component normal to the direction of air flow, and turning moment (yawing or pitching), which is the moment produced by the resultant air force tending to turn the model about its point of support.

These readings or drift can also be obtained in a wind tunnel by suspending the model by means of wires and noting the deflection.

Advantages of Wind Tunnel

The main advantages of the wind tunnel over other methods of testing are—

1. A convenient, portable, safe and relatively inexpensive method of obtaining valuable data for use in the proper design, analysis and performance prediction of all types of aircraft.

2. The ability to produce a steady wind and to control its velocity and direction for as long a period of time as is necessary for accurate observations.
3. The ability of manipulating the air flow in the vicinity of the model, and thus to measure the pressure of air just along the surface of the model.
4. The ability to repeat the conditions of a test at any time in order to check results.

Principal Types of Wind Tunnels

There are three distinct types of wind tunnels, namely: (a) the N. P. L. (National Physical Laboratory) of Great Britain, the Gothaer of Germany and the Eiffel of France.

(a) **N. P. L.** This type tunnel consists of a long uniformly square section channel, in which the model is supported in the center of the channel. The air is drawn through the channel by means of a propeller at the end of the tunnel. The center of the balance is located beneath the channel, where the experimenter takes his readings. A bell shaped collector is attached to the mouth of the channel, and horizontal sections of metal are placed in the channel section in order to strengthen the walls of the channel. The air is drawn through the channel beyond the working or testing section of the tunnel. The propeller expands into a larger circular section in which the propeller or suction blower is located. This propeller may be driven by means of a belt connected to a motor branch, the top and bottom of which are of twelve teeth in order to allow the propeller to turn in either direction. The air is then drawn into a separate room or building so that the air discharged from the diffuser is drawn into the collector. Wind tunnels of this type are used by the Massachusetts Institute of Technology, the Curtiss Aeroplane & Motor Corp., the Washington Navy Yard and the Bureau of Navigation. The tunnel is 10 ft. wide and operated at a 4 ft. per sec. P. D. with a 15 hp. electric motor, giving 30 mph. air speed. Certain Aeroplane Laboratories, by using a 100 hp. Curtiss motor direct-driven a propeller, obtain a range of velocity from 20 to 75 mph.

(b) **Gothaer.** This type differs from the N. P. L. and Eiffel tunnels. It provides a closed circuit, the testing portion of the channel being a square section. It has been extensively used for both land and aerial machines.

The tunnel is 5 ft. 6 in. square and a wind velocity of 30 mph. is obtained with a 30 hp. electric motor driving a blower. The large wind tunnel of the U. S. Navy Department is an E. D. square tunnel of this type and is operated by means of a 500 hp. electric motor driving a suction blower. A wind velocity of 15 mph. may be obtained, but tests are generally made at a speed of about 60 mph. Models of both airplanes and airships are tested in this tunnel.

(c) **Eiffel.** This type consists of a circular bell shaped collector, which is a tight cylindrical chamber and an expanding track or diffuser from the experimental channel to the suction blower. The tunnel is located in a large room and the air from this room is drawn into the bell shaped collector from which it passes through a honeycomb baffle to strengthen the flow, across the experimental chamber with a uniform velocity into the expanding track, from which the suction blower discharges it at a low velocity back into the room.

The large Eiffel tunnel has a 6½ ft. diameter air stream

from 4 to 72 mph.

The Curtiss 2 ft. wind tunnel at Garden City, Long Island, is of this type. It is operated by a 400 hp. Liberty engine direct-driven a three blade 12 ft. diameter propeller, and velocities from 4 to 30 mph. are obtained. The tunnel is 24 ft. 11 in. wide at its widest, and is 100 ft. long. The wind speed used for testing propeller models is also of the Eiffel type, and a wind velocity of 40 mph. is obtained by means of a 20 hp. reduction motor, half-driving a propeller

Apparatus

The wire suspension method requires the least expensive apparatus for determining the direct resistance of a model. This consists of two long fine steel wires for suspending the model, two horizontal wires with a ring at the middle of each end to support a small balance, a vertical wire to support a gauge, a telescope to measure the horizontal deflection of model, a means of determining the weight of the model and a

measuring tape for obtaining the length of the suspension. Two extra wires, weaker than the suspension wires, are necessary for taking the correction due to the tension of the suspension wires.

The aerodynamic balance embodies the mechanical principle of moments. It consists of a vertical arm and two horizontal arms at right angles to each other, and is free to pivot about horizontal knife edges so that a single point. The model to be tested is mounted to the top of the vertical arm and known weights are suspended from the horizontal arms. The balance is set at any working scale, in order to balance the air force on the model. The model and balance arms are mounted on knife edges restricting the motion of the model to either forward or side sideways motion, one at a time. The balance on the Curtiss 2 ft. tunnel provides for a point so that the lift and drift are both measured at the same time.

For testing the "airship" or "airship-like" the apparatus is made free to rotate about its vertical axis. A single horizontal arm connected to the vertical arm operates a single balance, or weighing scale which measures the turning moment directly on its blade.

Wind velocity is measured by means of a Pitot tube or else a Kiel gauge which has been calibrated with a standard Pitot tube.

(a) **Pressure distribution on model.**

A small copper tubing embedded in the surface of the model

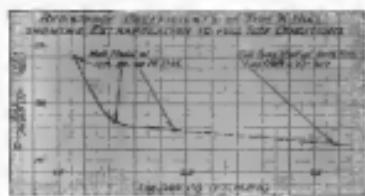


FIG. 1

is connected to a manometer by means of flexible tubing. Very small holes drilled in the copper tube near the surface of model permit the measurement of the pressure distribution along the model. During an observation all holes, excepting the one in question are plugged up with wax.

Models

Standard Conditions. The results of all wind tunnel tests are reduced to a standard condition of 15 deg. Cent and 760 mm. Hg., in order that they may be used and compared directly, without knowing the specific conditions.

Configurations. The models to be tested directly in the tunnel, the wind tunnel, are suspended directly in the model itself, but it is more convenient to have them suspended as airfoils, in order to apply them to lift and drag measurements and for comparison of the aerodynamic characteristics of various shapes.

The form of these coefficients depends upon the use of the bodies. For instance, in an airfoil where the lift and drift are directly related to the angle of the wings, other conditions remaining constant, the lift and drift coefficients are expressed in terms of angle by following formulas

$$L = \frac{K_L}{A^2} = \frac{1}{A^2} \cdot \frac{C_L}{D} \quad (1)$$

$$D = \frac{K_D}{A^2} = \frac{1}{A^2} \cdot \frac{C_D}{C_L} \quad (2)$$

where K_L and K_D are respectively the lift and drift coefficients, A the total area, D the total wing resistance in lb., at the area of the wings in sq. ft., and C the velocity in mph.

In an airship, where the lift or buoyancy varies directly with the volume, the resistance coefficient should be expressed in terms of volume as in the following formula:

$$C = \frac{g}{\rho (A^2)^{1/2}} \quad (3)$$

where C = resistance in lb.,
 g = acceleration of gravity in ft./sec.² = 32.2
 ρ = density of air in lb./cu. ft. = 0.0005 under standard conditions.

$$V = \text{velocity in ft./sec.}$$

This makes C a non-dimensional coefficient

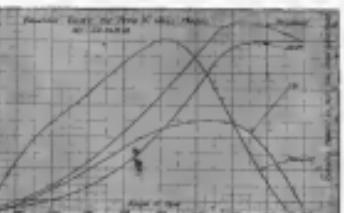


FIG. 2

Model to Full Scale

In order to make the results of model tests more nearly applicable to the full size machines or parts, it is now necessary to test the model in the wind tunnel at the same speeds as possible and then to plot these coefficients against the FL ratio, where F is velocity and L is the linear dimension. This model FL even with the highest possible wind tunnel size we

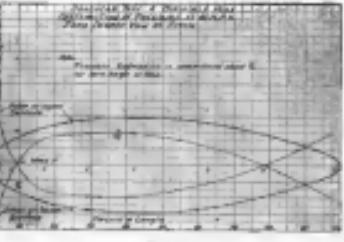


FIG. 3

comes very far below that of the full size ship, so small models are often plotted to a larger FL base and extrapolated to the full size conditions.

For airships it is more appropriate to use $(F/FL)^{1/2}$ as a base instead of FL .

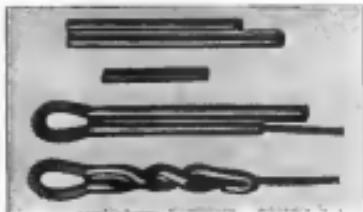
The model resistances are also plotted against velocity on logarithmic paper and the slope of this line gives the exponent of the velocity according to which the resistance varies. Fig. 1, lift, drift and moment readings are taken at various angles of deflection (incidence or yaw), then vector diagrams can

The McCabe Sleeve

By L. E. McCabe

The McCabe Sleeve is a wire rope fastener supplied by the use of continuous wires only and has been developed chiefly for use on aircraft. It is made up without the use of solder with attendant savings from acids, fluxes and overheating and has working tolerances not difficult for the workman to maintain. Its efficiency is high and uniform when the simple directions for making up are followed and inspection is as rapid as possible.

The sleeve itself is a copper construction comprising two parallel tubes, one of which is extended beyond the other, the extended portion being known as the neck. It is formed of



THE ILLUSTRATIONS SHOW THE McCABE SLEEVE, THE TWISTING TOOL, AND THE FINISHED JOINT.

specially rolled sheet copper by automatic machinery, bared between the tubes upon one side, thoroughly polished to remove scale, and tensioned to prevent corrosion action upon the cable and to secure a double measure to galvanized or coated cable. The cable is then twisted and tensioned and gauged to insure against difficulty in insertion of the cable.

Fig. 1 illustrates the 5/32 in. sleeve and handle both before and after application and Fig. 2 the tools used.

The first operation, in the making up of McCabe joints, requires tying the cable on each side of the plate to be secured about 5 in. apart. This is accomplished by the use of two or three strands of soft wire, each made of two or more tightly twisted together. The operation is necessary to prevent the strands of the cable and to bind the ends of the strands closely for easy insertion into the sleeves. The cable is then placed between sections of plates, shown in Fig. 3, and tensioned.

The end of plates is first inserted into the short tube of sleeve at the neck end (see Fig. 1), the binding wire loosened slightly and the cable passed through the binding wire and twisted by an 80° twist. The binding wire is then cut and the strands left uncut. It is next threaded through the end handle (see Fig. 1), and from that, using the same methods to prevent stretching, into the long tube up to the neck. The surplus cable, which has been pulled through the short tube to secure the binding wire, is then securely gripped back and the end handle is kept to the center of the plate, during the operation, to prevent kinks or sharp bends in the cable which would lower the strength.

The joint is now ready to be twisted (see Fig. 1), and special plates are applied, one Fig. 2. Care must be taken that the parallel sides of the plates face each other, so that the cable will be twisted parallel with the side of double tubes of the sleeve at the twisted point between the tubes. The sleeves are then twisted one and one-fourth turns in such direction that the strands between the joints are twisted tighter. Twisting in the opposite direction tends to decrease the efficiency about 3 per cent.

It is essential that the twisting be done along the longitudinal axis of the sleeve. After the plates are removed, the joint is held in one hand while the neck is gripped, not more than half way from the end, by the nose of the pliers, and bent over in such direction that the rib on the neck is outside. This bend is nearly 120° and the neck is completed by being plied between the prongs of the pliers nearer the base of the handle and creased down tight against the main body of the sleeve.

The joint is now complete (see Fig. 1), and the inspection consists of examining the end of the cable to see that the cable is in sight and that the neck is pressed down tight against the sleeve; it should also be noted that the sleeve is twisted properly, that is, in the right direction and along the longitudinal axis. If any changes are made the joint will be faulty, the defect will be shown in the surface of sleeve.

The design and development of this device began in the period when aviation was still in its infancy. The writer, while working on experimental work with gliders during 1913 and 1915, and with considerable difficulty in the use of piano wire, so substituted cable and conducted further trouble in making up a satisfactory cable joint.

Having been previously employed in telephone work and being familiar with the wire joints in use in that field, he invented a number of standard sleeves supplied for that purpose.



FIG. 2
TOOLS USED IN TWISTING THE McCABE SLEEVE.

From these, by a number of experiments and tests made rather crudely on account of the limited apparatus at hand, he was able to evolve a type of joint which gave much better satisfaction than the several types he had previously used. The same was used in the form developed, during the following three years on two airplanes built by himself, and proved thoroughly dependable under severe usage.

The original joint was made of a twisted pair of soft-wire and stranded wire sleeves, twisted one and one-half turns. Instead of the neck as now used the cable itself was extended beyond the sleeve, bent back and twisted down with friction tape. This stranding of the cable permitted a reduction in the number of turns from three and one-half to one and one-half thereby shortening the sleeve about 40 per cent, cutting down both the weight and load resistance.

The stranded ends of the cable, although tapered, had a ten-

Aug. 25, 1928

AVIATION

degree to increase frequently exposed, causing much discomfort and vibrations damage to the workmen who happened to come in contact with them. Later the idea of the neck as now used, was originated to overcome this and, upon patents being issued, the writer was taken up with the Frank B. Cook Co. of Chicago which had manufactured most of the sleeves used.

This company has been engaged on the manufacture of wire connectors and sleeves of various types for nearly twenty years and further development was undertaken at its factory.

A large amount of data for various types and sizes of wire joints were available and, with the aid of these tools and an extensive bench work, some 5000 or more samples of McCabe sleeves of various types, sizes, gauges, and materials were made and tested under varying conditions during 1916 and 1917 by the writer.

Weight is a factor and also the question of air resistance demands as small a point as possible. Comparatively, the McCabe joint is much lighter to stand three times in the face of the tensile strain, in half the length and weight less than the sleeve strain, in the face of the tensile strain.

In the early tests, breaking of the cable was considered to be a sufficient evidence of strength, especially as the breaks usually occurred in the region of strain, especially at the joints.

Later this was found to be faulty and thereafter, all tools were made comparative to test loops of cable from the same and with both the soldered and the served and soldered types of terminals.

As previously mentioned, experimental lengthwise wire joints were found to be unreliable, though the original wire joints were considered to be responsible for considerable variation in testing. From five to ten loops of each model of sleeve were usually tested at a time. The tools for twisting also have much bearing on this.

The knowledge of these facts necessitated the adoption of methods of manufacture which would not permit a sleeve to be drawn close to wire, but also the desire to have the purpose of simplifying the operations in making up the joint and making certain the many maintenance of tools that insure its efficiency.

There are several types of terminals which have high efficiency when made up properly, but many methods are available to work within tolerances that insure this. The very nature of the sleeve, which is a tube, and the fact that it is not a strain, as is the case with the terminals, is such that the terminals must be securely held in the McCabe joint and these are maintained mainly in its manufacture and the user has far more latitude in applying it than is possible with most of the types now in use.

In developing tools for sealing up the joint consideration was given the suggestion of progressive tools that would consist of a series of two or three tools each to reduce the time of the necessary operations, or all the seven sizes of sleeves which were being developed, that they might be made a part of the airplane's tool kit.

This required that the tools for the cable be modified in the tools and previous experience had shown that a gradual type of change was necessary to give service. Also this same type of development in the airplane's tools is of interest to be a part of the airplane's equipment.

The writer was taken up with Matthes Klein & Sons of Chicago, and with their cooperation various designs were made and tried out, leading to the design of tools shown in Fig. 2 which have been adopted with slight modifications in the shape of the jaws.

A set of Klein's Army pliers, as now supplied, is sufficient for making up all sizes of joints now made, with possibly the aid of a small pair of Klein's pliers to be used in cutting the end and for stretching and for tying the cable. A set of hand tools, which is very convenient when a wire is at hand, has been developed to substitute for one pair of pliers. The wire must be tensioned as the sleeves may be held in it while the wire is being twisted. The use of a hand tool will be as good as for the twisting. A single movement of the handle shears close and locks the pins upon the sleeve and a movement opposite releases. The handle of the pliers is supplied with a locking device of the familiar link type not so rapid in operation but still satisfactory.

Another problem, given a careful investigation, was the prevention of corrosion within the joint itself. The chemical engaged in this investigation found the previous experience of the Frank B. Cook Co. in its own wire plant to be the most satisfactory and therefore dependable in the conditions as cylinder and wire more favorable for the McCabe sleeve than the field.

While the investigation was being conducted, samples were made among a number of customers in the telephone field who had been using the wire sleeves for a number of years. These were found to be the purpose of securing a number of joints which had been in use for a number of years and no failure might be observed. Some samples were received which were stated to have withstood ten piano wires and the evidence of the wire to which it was attached indicated this. In spite of the fact that the wire outside the sleeve had rusted mostly through, the wire inside was found intact with the gauge wire 10 ft. long. It is not known what the joint would withstand with the conductivity of the wire due to the presence of tin, however, in the case of the telephone lines today in ungrounded conductors, the use of service, completely justifies the adoption of the same methods to ground against it in the McCabe sleeve. As a matter of fact, there are more remote for corrosion on the McCabe sleeve than in soldered types of terminals, especially if it has been used in the presence of soldering.

Development of the wire sleeve, based upon a similar type used in the served and soldered terminal and samples displayed by the type now used, has been offered. Instead of a soft wire, however, a tempered and plated wire is used, withstands far more wear and tear, conditions which the soft wire failed to meet. The combination with the sleeve presents a new appearance and its use will be considered as simplifying the operations of securing the cable through the sleeve. Comparative tests with other standard forms of sleeves show no appreciable difference in the case up to and including 1/4 in., delivering approximately 100 per cent efficiency. A slight drop in the efficiency is found in the two largest sizes and changes are being made to overcome the deficiency.

Under Table I will be found data on the several sizes now developed. The figures in the cable characters are given as well as the breaking strain and the maximum load. Figures are given which are the highest that have been found in the tests made and are not to be considered as the general performance of the cable. Although generally considered to be the rated strength of the cable is the most reliable basis to work from. Their purpose here is to indicate rather the capacity of the McCabe joint. The table of weights are for the capacity of the McCabe joint. The length of the cable is the length of the sleeve, less the distance after it is twisted. The length of the double tools is given before twisting is approximately the same as the wire after twisting.

Table II is a report of a test in 3/32 in. cable made for the purpose of securing data regarding elongation of the McCabe sleeve as compared with the served and soldered and the open sleeve type of joint. The test was made at the Robert W. Klein & Sons laboratory in Chicago on a 50,000 lb. capacity Brinell testing machine. The head had a squeeze velocity of 5% in. per minute. The nature of the tools are such that a weaker weight with a lower velocity is preferable but at the time it was not available.

It will be noticed that the McCabe joint has greater elongation than the other two types, especially up to the elastic limit of the cable, which was found to be approximately 75 per cent of the breaking strain from comparative elongations taken from the Brinell test. The tension strain cable has (see Klein's Report) as the "Final Annual Report of the Advisory Committee for Aviation," an elongation of 100 per cent times as much elasticity as a soft wire of the same material. This additional elasticity is the main reason for its use in place of solid wire. Solid wires do not create the same tension, however, during the additional movement allowed, a portion of the energy is absorbed, thereby reducing the magnitude to be released. Vibrations of the same amplitude do not occur in the cable as in the case of the wire when releasing energy and crystallization.

The McCabe joint offers the user the added advantage of still greater elasticity which permits loading the guys to the tension desired to maintain the machine in alignment and still allow a free movement to absorb shock and vibrations. Not being strained, the temper of the cable is not affected in any way and there is no chance for vibration to develop, as sometimes occurs with cables which have been subjected to the

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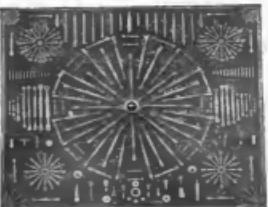
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